

Spot[®]

Transformative Mobility

Automate sensing and inspection, capture limitless data, and explore without boundaries.

Operate with Ease

Spot's vision system makes it easy to navigate around objects and over rough terrain. Control the robot from afar using an intuitive tablet application and built-in stereo cameras. Spot can also be teleoperated via Orbit™ desktop software.

Automate Data Collection

Program repeatable autonomous missions to gather consistent data. Flexible autonomy allows Spot to adjust to changes on its programmed path as desired. Missions can be launched from the Spot Dock for remote operations.

Customize for Your Needs








Spot can carry up to 14 kg (30 lbs) of sensing equipment. Our diverse payload ecosystem is ready for a variety of applications, from thermal and acoustic inspections to laser scanning and site progress monitoring.

Learn with Training and Support

We make it easy to get started with Spot. Our Support Center features a comprehensive collection of knowledge articles and discussion groups, product training options are available, and in addition to our one-year limited warranty, we offer premium service and support through a Spot Care subscription.

www.bostondynamics.com/products/spot

Features

-  14 kg (30 lbs) Payload Limit
-  90-Minute Run time
-  Object Avoidance
-  Stair & Complex Terrain Navigation
-  Manual & Autonomous Operation
-  IP54 Rated
-  Flexible API and Python SDK
-  Premium Service and Support

Industries



Manufacturing

Set Spot up to do autonomous inspection rounds or use the robot to create digital twins of a plant in advance of rework.



Construction

Inspect progress on construction sites, create digital twins, and compare as-built conditions to Building Information Modeling (BIM) autonomously with Spot.



Power & Utilities

Create autonomous routes or drive the robot to remotely perform inspections in electrified or radiation dense areas.



Mining

Create routine tunnel inspection routes and attach additional payloads to take measurements and ensure safe working conditions.



Oil and Gas

Create autonomous routes or drive the robot to remotely inspect facilities and improve site awareness of plant operations.



Public Safety

Drive Spot remotely to get eyes on dangerous situations and inspect hazardous packages from afar.

BostonDynamics



Specifications

Base Robot

DIMENSIONS

Length = 1100 mm (43.3 in)
Width = 500 mm (19.7 in)
Height (Sitting) = 191 mm (7.5 in)
Default Height (Walking) = 610 mm (24.0 in)
Max Height (Walking) = 700 mm (27.6 in)
Min Height (Walking) = 520 mm (20.5 in)
Net Mass/Weight (Spot with battery) = 32.7 kg (72.1 lbs)

LOCOMOTION

Max Speed = 1.6 m/s
Max Slope = ±30°
Max Step Height = 300 mm (11.8 in)

TERRAIN SENSING

Horizontal Field of View = 360°
Range = 4 m (13 ft)
Lighting = > 2 Lux
Collision avoidance = maintains set distance from stationary obstacles

CONNECTIVITY

WiFi = 2.4GHz / 5GHz b/g/n
Ethernet

AUDIO & VISUAL SIGNALS

Pre-configured behaviors for manual and autonomous operations
LED Brightness = Adjustable up to 1010 Lux
Max Projection Distance = 1.8 m in front of robot
Buzzer Volume = Adjustable up to 110 dB at 1 m distance from robot

ENVIRONMENT

Ingress Protection = IP54
Operating Temp. = -20°C* to 55°C

* Robot must be powered on at a minimum temperature of 0° C.

Travel Cases

ROBOT CASE

Includes robot and tablet
Length = 927 mm (36.5 in)
Width = 546 mm (21.5 in)
Height = 464 mm (18.25 in)
Net Mass/Weight = 47.6 kg (105 lbs)

POWER CASE

Includes two batteries and charger
Length = 810 mm (32 in)
Width = 530 mm (21 in)
Height = 300 mm (12 in)
Net Mass/Weight = 28 kg (61 lbs)

Payload Mounting

Max Weight = 14 kg (30.9 lbs)
Mounting Area = 850 mm (L) x 240 mm (W) x 270 mm (H)
Mounting Interface = M5 T-slot rails
Connector = DB25 (2 ports)

Power Supply = Unregulated DC 35-58.8V, 150W per port
Integration = Available software API and hardware interface control document

Spot Dock

DIMENSIONS

Length = 1140 mm (44.9 in)
Width = 414 mm (16.3 in)
Height = 403 mm (15.9 in)
Mass/Weight = 22.9 kg (50.5 lbs)

POWER

Input = 90-277 VAC
Output = 58V at 12A
Charge Time = 2-3.5 hours**

**Charge time varies based on table below

Ambient Temp.	80% charge	100% charge
25°C	50 min	2 hrs
35°C	2.5 hrs	3.5 hrs

ENVIRONMENT

Operating Temp. = 0°C to 35°C
Lighting = Ambient light required
Mounting = Bolt/tie down locations provided

CONNECTIVITY

Gigabit Ethernet passthrough to robot

CERTIFICATIONS

cTUVus Certified to UL 1564 and CSA C22.2 No. 107.2

Battery

Battery Capacity = 564 Wh
Average Runtime* = 90 mins
Standby Time = 180 mins
Recharge Time = 60 mins

Length = 324 mm (12.8 in)
Width = 168 mm (6.6 in)
Height = 93 mm (3.7 in)
Mass/Weight = 5.2 kg (11.5 lbs)

*Runtime may vary depending on payloads and environmental factors

Charger

Input Voltage = 100-240VAC 50/60Hz 8A Max
Output = 35-58.2 VDC, 12A Max
Length = 380 mm (15.0 in)

Width = 315 mm (12.4 in)
Height = 178 mm (7.0 in)
Mass/Weight = 7.5 kg (16.5 lbs)
Operating Temp. = 0°C to 45°C

Tablet

Height = 127 mm (5.0 in)
Width = 214 mm (8.4 in)
Depth = 10 mm (0.4 in)
Weight = 426 g (0.9 lbs)
Touch Screen Size = 8" diagonal

Resolution = 1920x1200
Ingress Protection = IP65

Joystick add-on available

Safety and Compliance, United States

Designed according to ISO 12100 for risk assessment and reduction methodology and IEC 60204-1 for electrical safety. See [Information for Use](#) for further details on intended uses.

Emergency Stop meets ISO 13850

EMC: FCC Part 15B
 Radio equipment: Incorporates a FCC Part 68 Certified radio system
 Laser product = Class 1 eye-safe per IEC 60825-1:2007 & 2014

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Contact

sales@bostondynamics.com
www.bostondynamics.com/products/spot

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